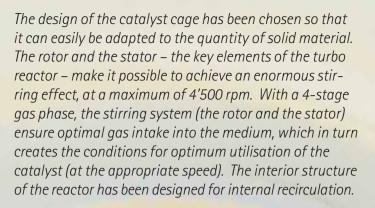
4-stage turbo reactor with the same basic structure for the frame and pneumatic system as type hpm-p. This model is fitted with a pneumatic cylinder so that the reaction vessel can be lifted towards the cover.

A turbo reactor can generally be used for gas and multiphase reactions. It is an important advantage in kinetic studies, the studies of catalyst deactivation and catalyst screening.

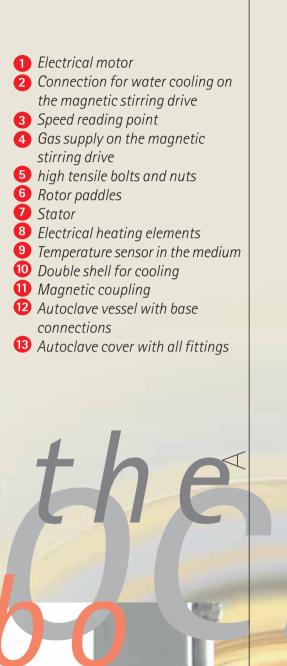


The «turbo» reactor can be used as a batch system or for continuous reactions.



Bore holes on the reactor cover - Two M16x 1.5 mm bore holes for

- Sitec valves, with cooling zone
- One M16 x 1.5 mm bore hole in
- front, to move the rotor into the working position
- One M16 x 1.5 mm bore hole for burst disc safety valve
- One M16 x 1.5 bore hole for pressure gauge and pressure
 - transducer
- One M16 x 1.5 mm bore hole with plug (reserve)



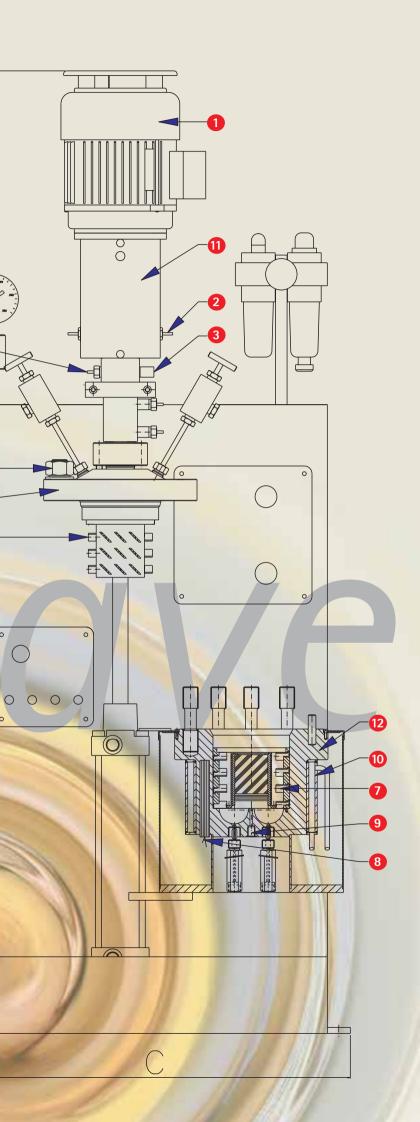
6

B

6

Bore holes on the reactor base

- Two M16 x 1.5 mm bore holes for Sitec valves, with cooling zone
- 1/4" bore hole with vertical pipe into the interior of the reactor, for thermal sensor type K (medium temperature)



External dimensions

Reactor frame with pneumatic system and drive A = height 1300 mmB = depth 520 mm C = width560 mm

Basic information

| Nominal volume | 700 ml |
|---------------------------|--------------------------------|
| Excess operating pressure | 300 bar |
| Operating temperature | 400°C |
| Speed | 4'500 rpm |
| Material | Nimonic 90 for reaction vessel |
| | and cover |

Flange lock

with hegh tensile bolts made of Nimonic 90 and nuts made of CrMo5 (5).

Seal

Conical metal-to-metal seal.

Heating

12 electrical heating elements, 250 Watt each (3000 Watt), ø 12.5 x 100 mm inserted into the reactor wall (8).

Temperature sensor

Temperature sensor, type K or type N, inserted into the reactor wall.

Cooling

Double shell for air or water cooling (10).

Drive

Electrical motor with nominal power of 1.1 kW, 3x240/400 V, 2-pole, 2'800 rpm, activated by frequency converter. The speed is adjusted with a potentiometer, from 200–4'500 rpm as the maximum limit (1).

Magnetic stirrer design

The magnetic stirring drive features a streamlined design for high speeds. The torque of the magnetic coupling is 6 Nm (11). The pressure shell between the inner and outer magnets is manufactured as a double shell for the water cooling system (2). There is another cooling zone on the carrier section of the MRK. Gas supply on the magnetic stirrer (4) and speed reading point (3) are included in the standard.

Bearings

Stainless steel ball bearings are used to mount the driven shaft, made of Mat. no. 1.4980.

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