# High-pressure autoclave with pneumatic lifting device – floor standing model, 2–10 litres

Our «prator» high-pressure autoclave offers a professional solution for your reactions. A pneumatic cylider raises and lowers the reactor vessel towards the cover, so that fixed pipework can be installed for the fittings on the reactor cover.

Customers can choose from premex reactor ag's range of add-on devices to be fitted on the reactor cover. As well as the standards, we offer numerous options including a pH sensor, IR sensor and level sensor for continuous reactions.

The pneumatic control and the cooling water valves are built into the rear wall of the reactor frame, with frontal access through a service opening.

## Bore holes on the reactor cover

- Magnetic stirrer drive
   Submerged tube with temperature sensor, type Pt100, type K or type N for measuring temperatures in the medium (there are 2 more sensors in the heating / cooling shell to control and monitor the heating).
- 3 Gas supply valve
- 4 Pressure release valve
  5 Valve with submerged tube as far
- as the reactor base, for sampling 6 Product feed valve
- 7 Manometer (pressure gauge) and pressure transducer



(exothermal) on request

12 Autoclave vessel

fittings

13 Autoclave cover with all

14 Base valve on request



## External dimensions

Reactor frame with pneumatic system, floor standing model A = height 1800 mm

B = depth 700 mm C = width 800 mm

## **Basic information**

Nominal volume2 Lt., 3 Lt., 5 Lt., 7 Lt., 10 Lt.Excess operating pressure100 bar, 200 bar, 325 bar,<br/>700 barOperating temperatureup to 350°C max.Speedup to 3'000 rpm max.MaterialMat. no. 1.4435 (AISI316L)<br/>Mat. no. 1.4571(AISI 316Ti)<br/>Mat. no. 1.4980 (AISI 660)<br/>Hastelloy C276, C22, B3<br/>Titanium Gr. 2

## Cooling

Cooling spiral cast into aluminium block or double shell cooling.

## Temperature sensors

One Pt100 temperature sensor, type K or type N in the submerged tube to measure the medium temperature, and two more sensors in the heating / cooling shell.

#### Drive

Electrical motor with nominal power of 120 W–550 W, 3x240/400 V, 4-pole, 1'400 rpm, activated with a frequency converter. The speed is adjusted using a potentiometer, from 200–2'000 rpm (maximum limit).

# Magnetic stirrer design

The magnetic stirrer drive features a streamlined design, and it is available in torques from 1 Nm–7 Nm.

## Flange lock

with high tensile bolts (CrMoV57) and nuts (CrMo5), up to 700 bar.

# Sealing

O-rings made of various materials, conical metal-tometal seal, or pure silver flat seal.

## Heating

*Electrical heating elements, 3000–7000 W thermal output, inserted in copper / aluminium block, or double shell for heat transfer oil.* 

#### Bearings

The driven shaft is mounted on ball bearings made of stainless steel or friction bearings made of PTFE/carbon.

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